



MISSION 3: Get Moving! Lesson 3 (Objectives 7-8)	Time Frame: 40-60 minutes												
<p><b>Project Goal:</b> Students will move the CodeBot by powering the wheels.</p> <p><b>Learning Targets</b></p> <ul style="list-style-type: none"><li>• I can import everything in the botcore library.</li><li>• I can enable the wheels.</li><li>• I can move CodeBot forward.</li><li>• I can rotate CodeBot clockwise and counterclockwise.</li></ul>	<p><b>Key Concepts</b></p> <ul style="list-style-type: none"><li>• The botcore library contains many functions and objects, not just leds. You can import the entire library using the wildcard *.</li><li>• The wheels must be enabled before running. If you forget this line of code, you will not get an error, the wheels just won't turn.</li><li>• A positive left wheel and negative right wheel will rotate clockwise. A negative left wheel and positive right wheel will rotate counterclockwise.</li></ul>												
<p><b>Assessment Opportunities</b></p> <ul style="list-style-type: none"><li>• Mission 3 Lesson 3 Log</li><li>• Submit completed program <b>MoveOut</b></li><li>• <a href="#">Mission 3 Obj. 7-8 Review Kahoot!</a></li></ul>	<p><b>Success Criteria</b></p> <ul style="list-style-type: none"><li><input type="checkbox"/> Import the entire botcore library</li><li><input type="checkbox"/> Move the CodeBot forward</li><li><input type="checkbox"/> Rotate the CodeBot clockwise</li><li><input type="checkbox"/> Rotate the CodeBot counterclockwise</li></ul>												
<p><b>Teacher Materials in Learning Portal</b></p> <ul style="list-style-type: none"><li>• Mission 3 Lesson 3 Slides</li><li>• Mission 3 Lesson 3 Log</li><li>• Mission 3 Lesson 3 Answer Key</li></ul>	<p><b>Additional Resources</b></p> <ul style="list-style-type: none"><li>• Paper protractors (learning portal)</li><li>• <a href="#">Mission 3 Obj. 7-8 Review Kahoot!</a></li><li>• <b>MoveOut</b> sample code (learning portal)</li></ul>												
<p><b>Vocabulary</b></p> <ul style="list-style-type: none"><li>• <b>Wildcard:</b> The * character; shorthand for “everything.”</li></ul>													
<p><b>New Python Code</b></p> <table border="1"><tbody><tr><td>from botcore import *</td><td>Import an entire library (* is a wildcard, which means everything)</td></tr><tr><td>motors.enable(True)</td><td>Turn on motors, must be done before motors will turn and wheels move</td></tr><tr><td>motors.run(LEFT, 50)</td><td>Turn left wheel forward at 50% power (use -50 for backward movement)</td></tr><tr><td>motors.enable(False)</td><td>Turn off motors</td></tr><tr><td>motors.run(LEFT, 30) motors.run(RIGHT, 30)</td><td>Move forward (straight line)</td></tr><tr><td>motors.run(LEFT, 30) motors.run(RIGHT, -30)</td><td>Rotate (+ left, - right is clockwise; -left, +right is counterclockwise)</td></tr></tbody></table>	from botcore import *	Import an entire library (* is a wildcard, which means everything)	motors.enable(True)	Turn on motors, must be done before motors will turn and wheels move	motors.run(LEFT, 50)	Turn left wheel forward at 50% power (use -50 for backward movement)	motors.enable(False)	Turn off motors	motors.run(LEFT, 30) motors.run(RIGHT, 30)	Move forward (straight line)	motors.run(LEFT, 30) motors.run(RIGHT, -30)	Rotate (+ left, - right is clockwise; -left, +right is counterclockwise)	
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<p><b>Real World Applications</b></p> <p>You've used some fundamental computer science and robotics principles:</p> <ul style="list-style-type: none"><li>• Controlling motors with specific timing and sequencing</li></ul> <p>This code is used in cars, robots, electric toothbrushes, and more!</p>													



## Teacher Notes:

- This lesson covers objectives 7 and 8 in Mission 3. You do not need to use the instructions in CodeSpace if you don't want to. All material is covered in the slides, including CodeTrek and meeting the goals.
- This lesson includes two “robot labs” that aren’t in the CodeSpace instructions. They give students a chance to try things out and experiment. ***The labs prepare students for the next lesson***, which is a navigation challenge.

## Extensions / Cross-Curricular:

- Make a poster or chart of Python commands.
- **SCIENCE:** Use the labs as science experiments. Talk about cause and effect. You can add an extra column to the lab reports and have students predict what will happen before running the code.
- **MATH:** Make a chart or graph from the data of the lab reports.
- Supports **language arts** through reading instructions and reflection writing.

## Preparing for the lesson:

- All CodeBots will need batteries for this lesson. The ‘bots will be moving around the room. Rechargeable batteries work fine.
- CodeBots will need space to move. Dedicate some floor space in your room for students to test their code.
- For the first robot lab, have tape measures or yardsticks available for measuring the distance a ‘bot moves.
- For the second robot lab, have a protractor available for measuring the angle the ‘bot turns. A paper protractor is included in the materials, and it doesn’t require any cutting to use. Just tape it to the floor.
- Look through the slides and workbook. Decide what materials you want to use for presenting the lesson. The slides can be converted to Google Slides. They can be projected on a large screen. The workbook (if used) can be printed or remain digital through your LMS and given to students.
- Be familiar with the mission log assignment and the questions they will answer. Prepare the assignment to give through your LMS.
- If you have a word wall, or another form of vocabulary presentation, prepare the new term.

## Lesson Tips and Tricks:

### Teaching tip:

You can use a variety of discussion strategies to get the most engagement from your students. For example, you can have students write their answers before asking anyone for an answer. You can use one of many think-pair-share methods. You can have students write their answer and share with someone, and then have other students share answers they heard from their peers. You can randomly select students to answer.

### Pre-Mission Warm-up: -- slide 2

Students can write in their log first and then share, or discuss first and then write in their log.

- Question: What are some common programming errors you have made during this mission?
- Question: How can you avoid the errors, or identify them when they are made?
- The questions can help students focus on the programming process. Discussing their answers can be beneficial to the students in the class, to normalize mistakes and foster a growth mindset.

### Mission 3 Lesson 3 Activities:

Each student will complete a Mission Log. Students could work in pairs through the lesson, or they can work individually. They will need a CodeBot and cable for the lesson. For the robot labs, they will also need a measuring stick (or tape) and a protractor.

### Teaching tip: Objective 7 Introduction -- slide 3

The slide gives important information on what to do before writing code that moves CodeBot. Students answer a question in the mission log.



### **Teaching tip: Objective 7** -- slides 4-6

These slides show the code students will use for the first iteration of their program. It covers the same information as the instructions in CodeSpace and can be used as an alternative.

### **Teaching tip: Objective 7 Activity** -- slides 7-8

This slide helps students meet the goal for objective 7. The code from CodeTrek is included. Students do not need to unplug CodeBot when they run the code. It is simply going to spin, so it can remain on their desk.

### **Teaching tip: Objective 7 Robot Lab** -- slides 9-12

This is an added lab to give students more experience with moving their 'bot, and a chance to try out the new code. For the lab, students will need space on the floor and a way to measure distance. This can be a little tricky the first time. Students must run the code first to load the program on CodeBot. Here is my suggestion, and as a teacher you can model this first:

- Run the code with the cable attached (this loads the program).
- When the code runs, hold the 'bot by its back, avoiding contact with the wheels.
- The wheels will turn in the air as the program runs.
- Then disconnect the 'bot from the cable.
- Set the 'bot on the floor, at a starting line, next to the measuring stick.
- Press the "REBOOT" button.
- The program will run again, without a cable.
- Measure the distance.
- Then return to the computer, make changes to the code, and reconnect the 'bot.
- Start the process over again for each code change.

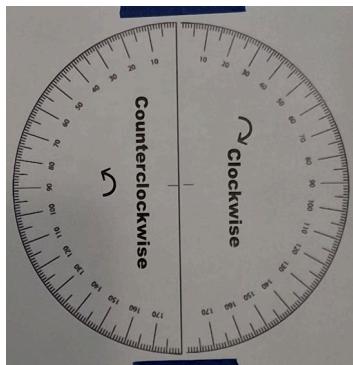
### **Teaching tip: Objective 8** -- slide 13

This is a very short objective. The slide discusses the code to rotate CodeBot.

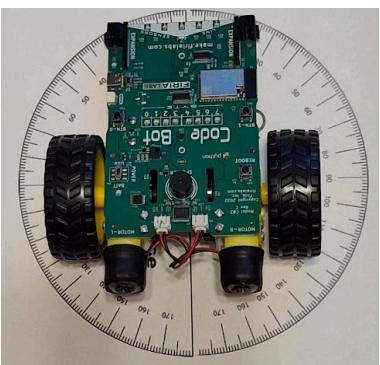
### **Teaching tip: Objective 8 Robot Lab** -- slides 14-17

The robot lab incorporates the goal for the objective, instead of doing it separately. If you are not doing the lab, you can just have students meet the goal. If students do the lab, the first trial meets the goal for the objective, and then they can continue to experiment and try out different combinations of powers and delays. Students will need a protractor to measure angle. You may need to review clockwise and counterclockwise since students may not use a traditional analog clock anymore. A paper protractor is provided in the teacher materials. Help the students know how to orient the protractor. Then measuring the angles should be fairly easy. If a 'bot goes past 180 in either direction, students will need to count past 180, since the protractor will not have those angles marked.

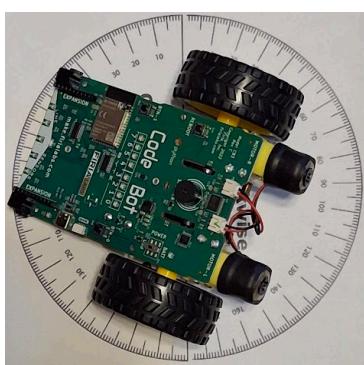
Protractor orientation:



CodeBot starting position:



Ending position (check angle):



**Optional:** Mission 3 Obj 7-8 Kahoot! Review.

A review Kahoot! is available for this lesson. You can do the Kahoot together as a class, or assign it independently.



 **Post-Mission Reflection:**

The post-mission reflection asks students to think about and review what they have learned in this lesson.

You can use an extension or cross-curricular activity as post-mission activity.

You can use the Mission 3 Obj. 7-8 Kahoot as a lesson review. (link above)

End by collecting the Mission 3 Lesson 3 Log.

**SUCCESS CRITERIA:**

- Import the entire botcore library
- Move the CodeBot forward
- Complete Robot Lab #1
- Rotate the CodeBot clockwise
- Rotate the CodeBot counterclockwise
- Complete Robot Lab #2